

Your Thesis Title



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In partial fulfillment of the requirements for the degree of
Master of Science in Engineering in Computer Science

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Acknowledgements

Write here your acknowledgements...

Thesis dedication goes here...

Abstract

The abstract goes here. The abstract should be self-contained and:

- clearly state the problem dealt with by the thesis;
- give a synthetic description of the proposed solution;
- highlight the sense in which the proposed solution enhances the state of the art.

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Chapter 1

Introduction

1.1 Motivations

1.2 Context of the Study

1.3 Objectives and Contributions

1.4 Overview of the Thesis

Chapter 2

State of the Art

Summary

Describe here the state of the art of the research pertaining to this thesis. This part should contain all the relevant publications in the area with the corresponding citations. The cited works should be briefly described critically assessed.

2.1 Section One name

2.1.1 Subsection One name

Chapter 3

System's Architecture

Summary

short summary of the chapter...

One or more chapters should be devoted to the description of the proposed approach...

In particular, this chapter describes the design adopted by this research to achieve the aims and objectives stated in the Introduction.

3.1 Section 1

Chapter 4

Methodology

Summary

Discuss here the methodology used in the study, the stages by which the methodology was implemented, and the research design; For examples, one section details the participants in the study, another section lists all the instruments used in the study and justifies their use; another section outlines the procedure (algorithms, code,..) used; a section discusses how the data was analysed, etc..

4.1 Section 1

Chapter 5

Experimental Results

Summary

Details all the results of your study here (exploits graphics for results visualization). This chapter should also contain a full discussion, interpretation and evaluation of the results.

5.1 Section 1

Chapter 6

Conclusions

Conclusions should summarize the problem, the solution and its main innovative features, outlining future work on the topic or application scenarios of the proposed solution.

References

- [1] B. Rim and L. Schiaratura, “Gesture and speech in fundamentals of nonverbal behavior,” 01 1991.
- [2] E. Coronado, J. Villalobos, B. Bruno, and F. Mastrogiovanni, “Gesture-based Robot Control: Design Challenges and Evaluation with Humans,” 05 2017.